

Harmonic Stability in Power Electronic Based Power Systems

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Speaker - Introduction



Xiongfei Wang

- Full Professor, KTH Royal Institute of Technology, Sweden
- **Professor (part-time)**, AAU Energy, Aalborg University, Denmark
- Visiting Professor, Hitachi Energy Research Center, Sweden
- Executive Editor (EiC), IEEE Transactions on Power Electronics Letters
- **10 IEEE Prize Papers** in Transactions and Conferences
- IEEE Fellow for contributions to "power electronic based power systems"
- 2019 IEEE PELS Sustainable Energy Systems Technical Achievement Award
- 2022 The Isao Takahashi Power Electronics Award

Xiongfei Wang received the B.S. degree from Yanshan University, China, in 2006, the M.S. degree from Harbin Institute of Technology, China, in 2008, both in electrical engineering, and the Ph.D. degree in energy technology from Aalborg University, Denmark, in 2013. From 2009 to 2022, he was with Aalborg University where he became an Assistant Professor in 2014, an Associate Professor in 2016, a Professor and the founding Leader of Electronic Power Grid (eGRID) Research Group in 2018. From 2022, he has been a Full Professor with KTH Royal Institute of Technology, Stockholm, Sweden, and a part-time Professor with Aalborg University, Denmark. From 2023, he has also been a visiting professor at Hitachi Energy Research Center, Vasteras, Sweden.

His current research interests include modeling and control of power electronic converters and systems, stability and power quality of power-electronic-based power systems, and high-power converters.

Power Electronics - Key Technology for Modern Grids



Switched-Mode Power Semiconductor Devices: higher efficiency and lower levelized cost of energy Digital Control: fully programmable, wide-timescale control dynamics

Power Electronic Based Power Systems



Transmission/Distribution

Consumption

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KTH Harmonics and Wideband Control of Power Electronics



LC Resonances of Converter Filters and Power Cables

> Use of high-order passive filters for switching harmonics attenuation



L-filter



LLCL-filter



LC-filter



LCL + trap filter



LCL-filter



Mutli-trap filter

Power cables





Harmonic Stability in Future Electronic Power Systems

- Resonance propagation in renewable clusters, industrial plants, and power grids
- Abnormal harmonics due to grid-converter interactions
- Cross-frequency coupling oscillations in multiple converters





VSC-HVDC + Offshore Wind

Two-Level VSC filter resonance Type-3 (DFIG) wind turbine



- World's first High-Voltage Direct Current (HVDC) connecting offshore wind farm
- Harmonic instability tripped the offshore wind farm [1]
- 3 years behind schedule at a cost of €3 billion [2]

[1] M. Larsson, "Harmonic resonance and control interoperability analysis of HVDC connected wind farms," IEEE eT&D, Aalborg, 2017.
[2] https://en.wikipedia.org/wiki/BARD_Offshore_1

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VSC-HVDC + Offshore Wind

Two-Level VSC filter resonance Type-3 (DFIG) wind turbine



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MMC-HVDC Transmission

Instability of current control in weak ac grid



Electrification of Railways

Locomotives is out of control because of abnormal harmonics





- Connection of a cable at 0.1 s

C. Zou, H. Rao, S. Xu, et al., "Analysis of resonance between a VSC-HVDC converter and the ac grid," *IEEE Trans. Power Electron.*, vol. 33, no. 12, pp. 10157–10168, 2018.
 C. Buchhagen, M. Greve, A. Menze, and J. Jung, "Harmonic stability-practical experience of a TSO," *Proc. 15th Wind Integration Workshop*, pp. 1–6, 2016.





Harmonic instability in railway traction power supply system - 15-75 times fundamental frequency [1]

- Derating surge arrester due to harmonic resonances - short-circuit fault

[1] K. Song, M. Wu, S. Yang, Q. Liu, V. G. Agelidis, and G. Konstantinou, "High-order harmonic resonances in traction power supplies: a review based on railway operational data, measurements and experience," *IEEE Trans. Power Electron.*, vol. 35, no. 3, Mar. 2020.

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Harmonic, Resonance, and Instability





- Re{*Y_{cl}*}>0: stable, yet underdamped Harmonic
- Re{*Y_{cl}*}=0: critically stable, zero-damped Resonance
- Re{*Y_{cl}*}<0: unstable, negatively-damped Instability

KTH Harmonic, Resonance, and Instability



[1] X. Wang and F. Blaabjerg, "Harmonic stability in power electronic based power systems: concept, modeling and analysis," IEEE Trans. Smart Grid, vol. 10, no. 3, pp. 2858-2870, May 2019.





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Harmonic, Resonance, and Instability



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Converter Modeling for Harmonic Stability Analysis

1970 Persson [1] - thyristor HVDC Frequency response analysis Describing Function with single sinusoidal inputs For control design	198 Ngo [3] - State-Spa with Park DQ-frame For contr	6 PWM converter ace Averaging transformation e linearized model rol design	Mattave [5] - thy Dynami Fourier	P7 elli, Verghese, Stankovic ristor FACTS devices ic Phasor with time-variant coefficients htrol design	Rico, I STATO contro Doma	03 Madrigal, Acha [7] - COM with phase angle I, Extended Harmonic in (EHD) armonic analysis	Cesp effec Harm Desc For c	bedes and Sun [11] - stability t of PLL on PWM converter nonic Balance, Multi-Input cribing Functions
 1985 Sakui and Fujita [2] - th rectifier, Switching Fur model w/o firing angle variation considered For harmonic analysit 	nyristor action is	1989 Larson, Baker, McIver [4] thyristor HVDC, numerica simulations derived Harm Cross-Coupling Matrix For harmonic/control a	- al nonic nalysis	2000 Mollerstedt [6] - locomotiv inverter, Harmonic State-S (HSS) modelling, Harmon Transfer Matrix For harmonic stability a	e Space ic nalysis	2007 Harnefors [8] - DQ-frame m with the phase variation; Wen, Boroyevich, et, al [9], Rygg, Molinas, Zhang, [10] For control design	odel 2016 , 2016	2016 Wang, Harnefors, Blaabjerg [12] - Unified Impedance Model from <i>dq</i> -frame to <i>αβ</i> -frame, 2 nd -order Harmonic Transfer Matrix For control design

Converter Model Validation - Frequency Scan



Converter Model Validation - Frequency Scan





Converter Model Validation - Frequency Scan

Impedance measurement software – commercialized

AIM Toolbox Measurement Settings PSCAD Parameters	– – ×		
Parameters Import Settings Export Settings Frequency Range fstart (Hz) fbound (Hz) 300 fend (Hz) 5000.0 System Parameters	Resolution Freq increment Log scale N1 20 N2 10 Simulation parameters Tsnp (s) 5.0 Tstep (µs) 5.0	$\begin{bmatrix} 20 & -40 \\ \times & -60 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\$	- Y _{VSC12} (s) Measurement
f1 (Hz) 50 ▼ Perturbation ✓ Broadband perturbation injection	Run Open results	$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 $	- Y _{VSC22} (s) Measurement
	DEPARTMENT OF ENERGY TECHNOLOGY AALBORG UNIVERSITY https://www.et.aau.dk/research-programmes/egrid/	$\begin{bmatrix} 50 & 90 \\ -90 \\ -180 \\ 10^0 & 10^1 \\ f(Hz) \end{bmatrix} \begin{bmatrix} 50 & 90 \\ -90 \\ -180 \\ -180 \\ -180 \\ -180 \\ -180 \\ -10^0 \end{bmatrix} \begin{bmatrix} 50 & 90 \\ -90 \\ -90 \\ -180 \\ -180 \\ -10^0 \end{bmatrix}$	$10^{1} f(\text{Hz})^{10^{2}} 10^{3}$

TRĀNSNET BW

Software users







- Fully automated, PSCAD/EMT compatible
- Impedance matrix in different reference (dq or $\alpha\beta$) frame
- Used by Europe's leading TSOs in multiple commercial projects







Digital current control of grid-connected converter – Proportional controller + L-filter



- Ideal inductor with zero parasitic resistance
- Re{ Y_{1d} }<0 introduced by digital control delay T_d





Frequency-Domain Impedance Passivity Control



Grid-forming (GFM) battery energy storage systems shall present a non-negative resistance within 0-300 Hz [1]

- In low frequency range, grid-connected converter is inherently non-passive at 0 Hz (dq-frame), or 50 Hz ($\alpha\beta$ -frame)
- Nature of constant power operation, e.g., P = ui
- Impedance matrix is required for the frequency range below 100 Hz ($\alpha\beta$ -frame)
- Insufficient, unnecessary stability criterion

GFM battery energy storage system shall present a non-negative resistance within 0-47 Hz and 53-250 Hz [2]

[1] NERC, "Grid forming functional specifications for BPS-connected battery energy storage systems," Sept. 2023.

[2] FINGRID, "Specific study requirements for grid energy storage systems," Jun. 2023.



Frequency-Domain Impedance Passivity Control

- > A linear, continuous system G(s) is **passive** if
 - G(s) is stable, no right half-plane poles
 - $\operatorname{Re}{G(j\omega)} \ge 0, -90^{\circ} \le \arg{G(j\omega)} \le 90^{\circ}$
- > A cascaded dynamic system is **stable** if
 - All subsystems G(s), H(s) are passive
 - Sufficient, but not necessary, condition
 - Increasingly adopted by industry



 $-180^\circ \leq \arg\{G(j\omega)H(j\omega))\} \leq 180^\circ$

- Minimization of control delay
 - Multi-sampling control
 - Hysteresis current control





Hardware solution – active damper based on high-frequency switching power converter



Hardware solution – active damper based on high-frequency switching power converter

- Paralleled VSCs w/o AD



- Paralleled VSCs w/ AD



Hardware solution – active damper based on high-frequency switching power converter



Grid-Forming Control Driven by Transmission System Operators (TSOs)



Initial Idea behind Grid-Forming Control – A voltage source in synchronism with other power sources





Synchronous machines



Power electronic converters



A deeper dive into difference between legacy grid-following control and grid-forming control

Control Principle	Grid-Following Converter	Grid-Forming Converter
Synchronization	 Reliance on external voltage Voltage-based synchronization Phased-Locked Loop (PLL) or equivalent 	 Self-synchronization Power-/current-based synchronization PLL may be used [1], [2]
Operation mode	- Current source in the sub-transient timeframe	- Voltage source in the sub-transient timeframe
Active power (<i>P</i>) control	- P - ω droop by measuring ω ; constant P	- P - ω droop without measuring ω ; constant P
Voltage and Reactive Power (Q) control	 Voltage magnitude (V) control Q-V droop, constant V, constant Q 	 Voltage vector control, critical to voltage stiffness <i>Q</i>-<i>V</i> droop + <i>P</i>-ω droop
Current control	Fast current control with limited response speedReference tracking and disturbance rejection	 Fast (natural) response speed within current limit Overcurrent limiting + impedance shaping [3]



- Harmonic stability differs from harmonic resonance in its dependence on converter control dynamics
- Impedance modeling of converter for harmonic stability analysis
 - Negative real part of converter impedance causes harmonic instability
 - Origin of negative real part of converter impedance time delay of current control, constant power operation
- Advancements in mitigating harmonic instability are demanded
 - Impedance passivity control sufficient, but not necessary, condition for harmonic stability
 - Active damper based on high-frequency, high-bandwidth converter more flexible than passive dampers
 - Grid-forming capability being required soon by power system operators

ThankYou

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